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P.M. Petrov, ScD.,

I.V. Grozniy, PhD

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Ключевые слова: текст, название, страница

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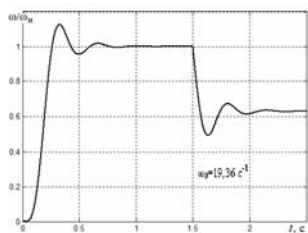
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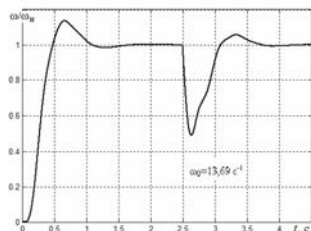
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a



б

Рис.1. Переходные характеристики в системе управления со статическим (а) и астатическим регулятором (б) при различных значениях ω_0

Figures from the graphs on the axes themselves have to specify quantities and their units (in the y-axis - to the left of the axis along the horizontal axis - the axis below). If one number is given by two or more images, they are designated as the English alphabet, a, b, c, etc. without parentheses, as shown in fig. A.

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$$k_{Wv} = \frac{\sin[\pi \cdot v / 6]}{\sin[\pi \cdot v / (6 \cdot q_6)]} \times \cos\left[\frac{\pi \cdot v \cdot (4k - 1 - n^*)}{4m_K}\right]. \quad (1)$$

The formulas for the transfer is permissible to break on signs +, -, =, ×, repeating them in both lines.

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Д. Г. Коренівський – К. : Ін-т математики, 2006. – 111 с.

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2. Суберляк О. В. Технологія переробки полімерних та композиційних матеріалів : підруч. [для студ. вищ. навч. закл.] / О. В. Суберляк, П. І. Баштанник. – Львів : Растр-7, 2007. – 375 с.

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3. Акофф Р. Л. Идеализированное проектирование: как предотвратить завтрашний кризис сегодня. Создание будущего организации / Р. Л. Акофф, Д. Магидсон, Г. Д. Эддисон. – Днепропетровск: Баланс Бизнес Букс, 2007. – 265 с.

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Периодические издания:

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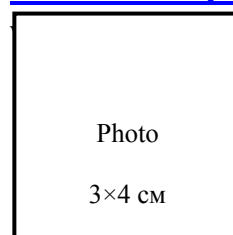
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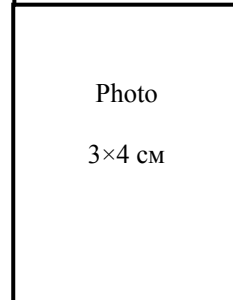
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